

파스텍 신제품 소개

2018. 11. 23
FASTECH



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 - Ezi-Robo ELGC
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- ❖ **Ethernet Type Closed Loop Stepping System**
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 - Ezi-MOTIONLINK Plus-E
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- ❖ **EtherCAT Type Closed Loop Stepping System**
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 - Ezi-SERVOII EtherCAT ALL
 - Ezi-SERVOII 4 Axes drive
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 - Ezi-SPEED

FESTO



Ethernet 타입 제어기 내장형
Closed Loop Stepping System

“FESTO Mini Slide 로봇 제어”

EGSC-BS + **Ezi-SERVO[®] II Plus-E**

Closed Loop Stepping System

Ezi-SERVO[®] II Plus-E
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



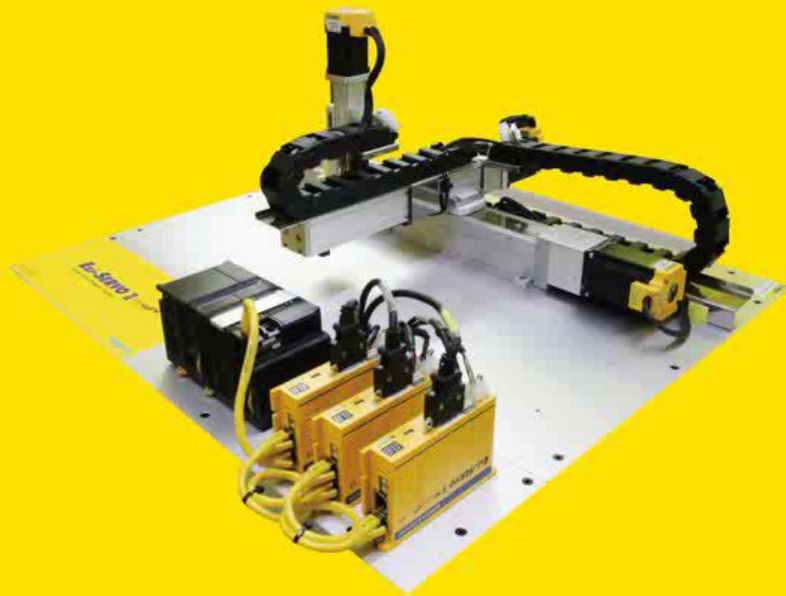
Closed Loop Stepping System
with embedded controller
based on **Ethernet**
“Force control (Push & Pull)”

ELGC, EGSC + **Ezi-SERVO**® II EtherCAT®
Closed Loop Stepping System

5

Ezi-SERVO® II EtherCAT®
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



EtherCAT Network 기반
Closed Loop Stepping System

“EtherCAT을 통한 FESTO 직교 로봇 제어”

Ezi-SERVO®
Closed Loop Stepping System

ELGC-BS + Ezi-SERVO® II EtherCAT®
Closed Loop Stepping System

Ezi-SERVO® II EtherCAT®
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



EtherCAT Network 기반
Closed Loop Stepping System

“EtherCAT을 통한
FESTO 4축 로봇 제어”

Ezi-SERVO®
Closed Loop Stepping System

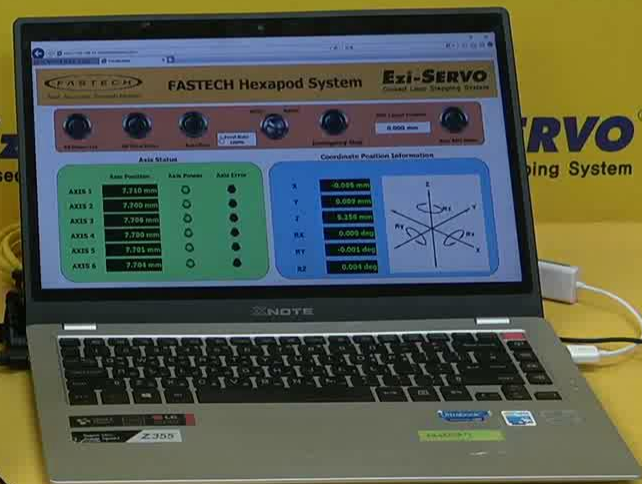
EGSC + Ezi-SERVO II EtherCAT[®]

Closed Loop Stepping System

7



6 Axis Hexapod
(FESTO, EGSC-BS)



Ezi-SERVO II EtherCAT + FESTO Hexapod

EXCM + **Ezi-SERVO[®] II** CC-Link
Closed Loop Stepping System

FESTO



CC-Link Network 기반
Closed Loop Stepping System

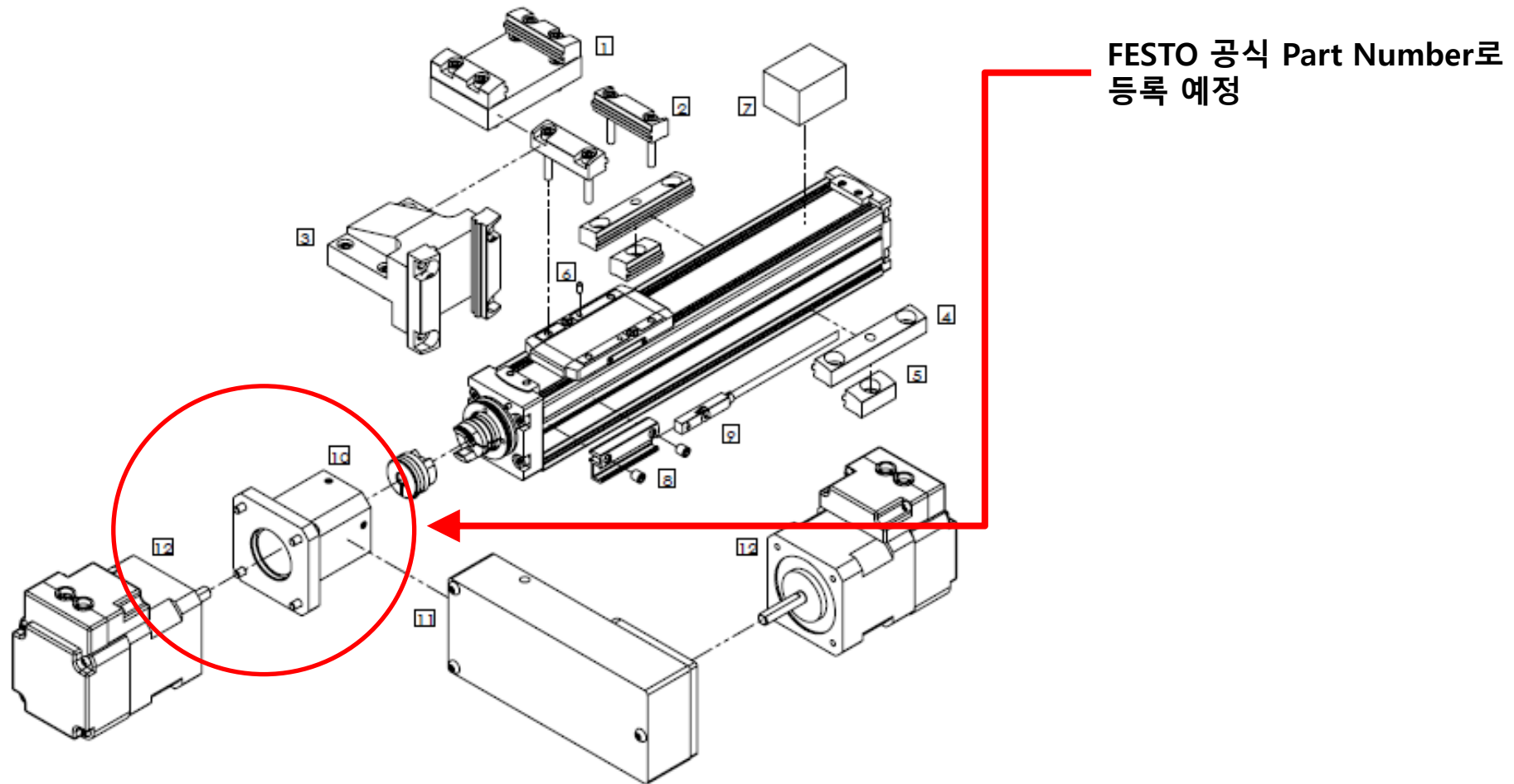
“CC-Link 를 통한
FESTO H-Portal 고속 단팻치 모션”

Ezi-SERVO + FESTO Actuator 특징점

- ❖ “One size down” : 한 치수 작은 actuator와 별도의 adapter 없이 간편 조립
- ❖ 자석 내장으로 간편 sensor 부착 별도의 sensor dog 불필요
- ❖ Ball screw 및 Guide 일체형 초소형 단축 Actuator (EGSC-BS)
- ❖ Stainless steel cover 기본 부착 clean room class 1,000 인증 (ELGC BS, ELGC TB)
- ❖ 2 축 동시 Belt 구동 : X/Y 2 축 최소 높이 구현 및 최대 Torque 사용 가능 (EXCM)
- ❖ 다양한 산업용 network 호환성 (Ethernet, EtherCAT, CC Link 등)

공식 협력 (FESTO KOREA & 파스텍)

❖ Ezi-SERVO Motor + FESTO Actuator 결합

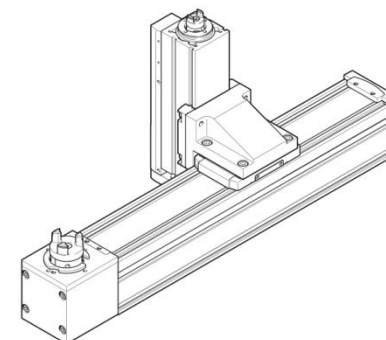
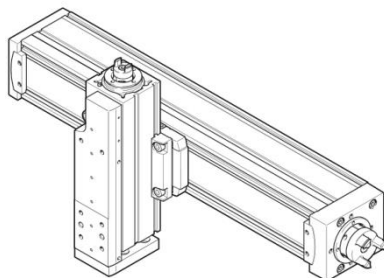
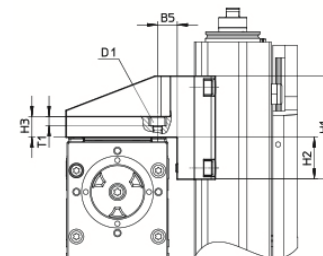
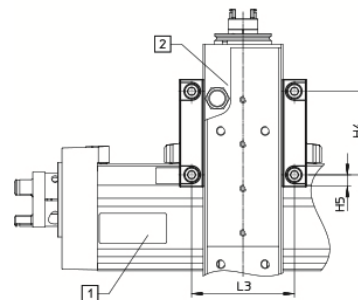
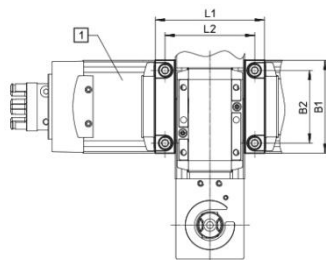
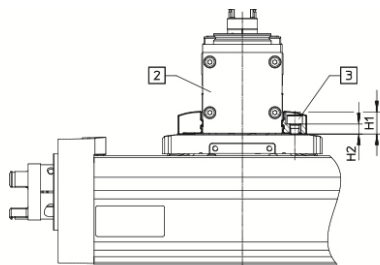


FESTO Actuator 주요 Concept

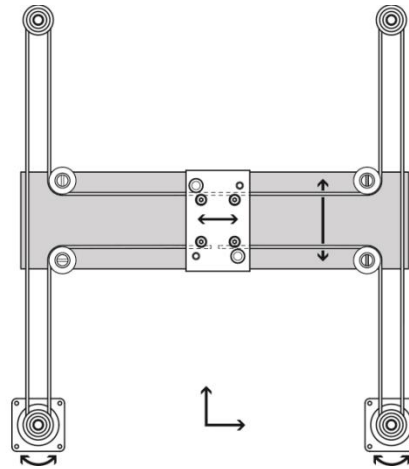
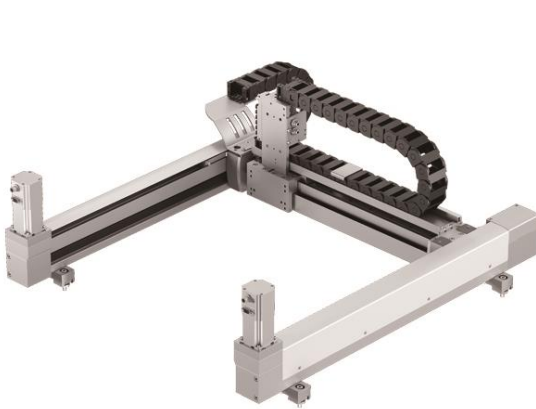
❖ Lego 조립 Concept : 간편 조립, 초소형, 최적 비율 설치 공간



표준 설치 Bracket



FESTO Actuator 주요 Concept (EXCM)



	+	•	-
+	↶	↗	↘
•	↗	•	↘
-	↶	↗	↘

- ❖ X/Y 2축 하나의 belt로 연결 X/Y 2축 을 1축 높이로 구성
- ❖ 2개 모터 동시 구동으로 최대 torque 구동 및 최소 가반 중량

Ezi-Robo-EGSC, ELGC, EXCM 저가형 Actuator

Ezi-Robo®

Actuator series Driven by Ezi-SERVO

- Compact Footprint with built-in Linear Guide & Ball Screw
- "One-size down" : No adapter for assembly
- High Accuracy (up to $\pm 0.02\text{mm}$) and Strokes up to 200mm
- Various Field Networks such as EtherCAT, Ethernet, CC-Link

EGSC-BS

Ezi-Robo®

Actuator series Driven by Ezi-SERVO

- Compact Footprint with built-in Linear Guide & Ball Screw
- "One-size down" : No adapter for assembly
- High Accuracy (up to $\pm 0.015\text{mm}$) and Strokes up to 1,000mm
- Various Field Networks such as EtherCAT, Ethernet, CC-Link

ELGC-BS

Ezi-Robo®

Actuator series Driven by Ezi-SERVO

- Flat and compact size & Cleanroom class 1,000
- Flexible motor mounting & modular concept
- High payload up to 3 kg, high Accuracy (up to $\pm 0.05\text{mm}$) and Strokes up to 700 x 360mm
- Various Field Networks such as EtherCAT, Ethernet, CC-Link

EXCM



FASTECH
Fast, Accurate, Smooth Motion



FASTECH
Fast, Accurate, Smooth Motion



FASTECH
Fast, Accurate, Smooth Motion

Ezi-SERVO®
Closed Loop Stepping System

Ezi-SERVO + Igus cantilever

Ezi-SERVO® II EtherCAT[®]
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



Closed Loop Stepping System
based on **EtherCAT**

**“IGUS 3 Axis Cantilever
Robot Control”**

Ezi-SERVO®
Closed Loop Stepping System

Ezi-SERVO + Igus Robolink

Ezi-SERVO® II EtherCAT
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



Closed Loop Stepping System
based on **EtherCAT**

“Multi-joint RoboLink”

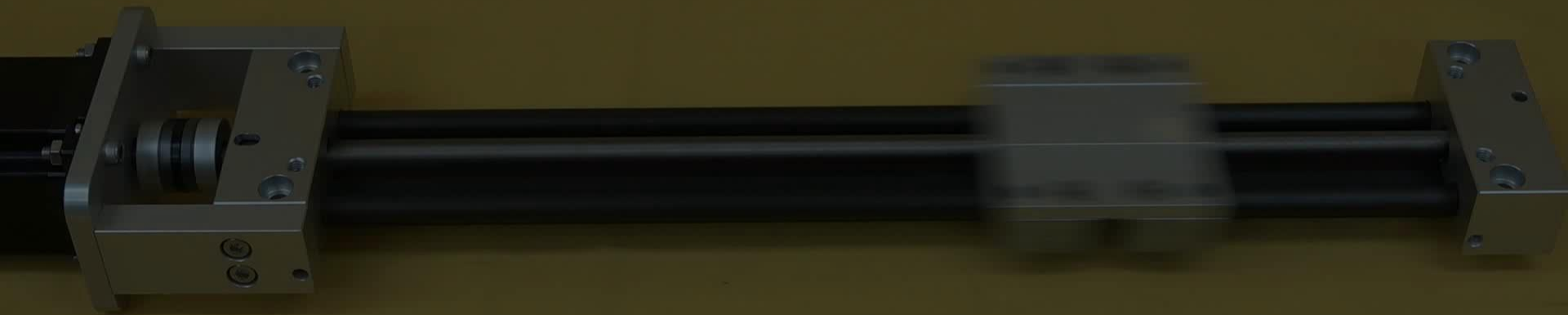
Ezi-SERVO®
Closed Loop Stepping System

Ezi-SERVO + Igus SLW & ZLW

op Stepping System

Closed Loop Stepping System

Closed Loop Stepping System

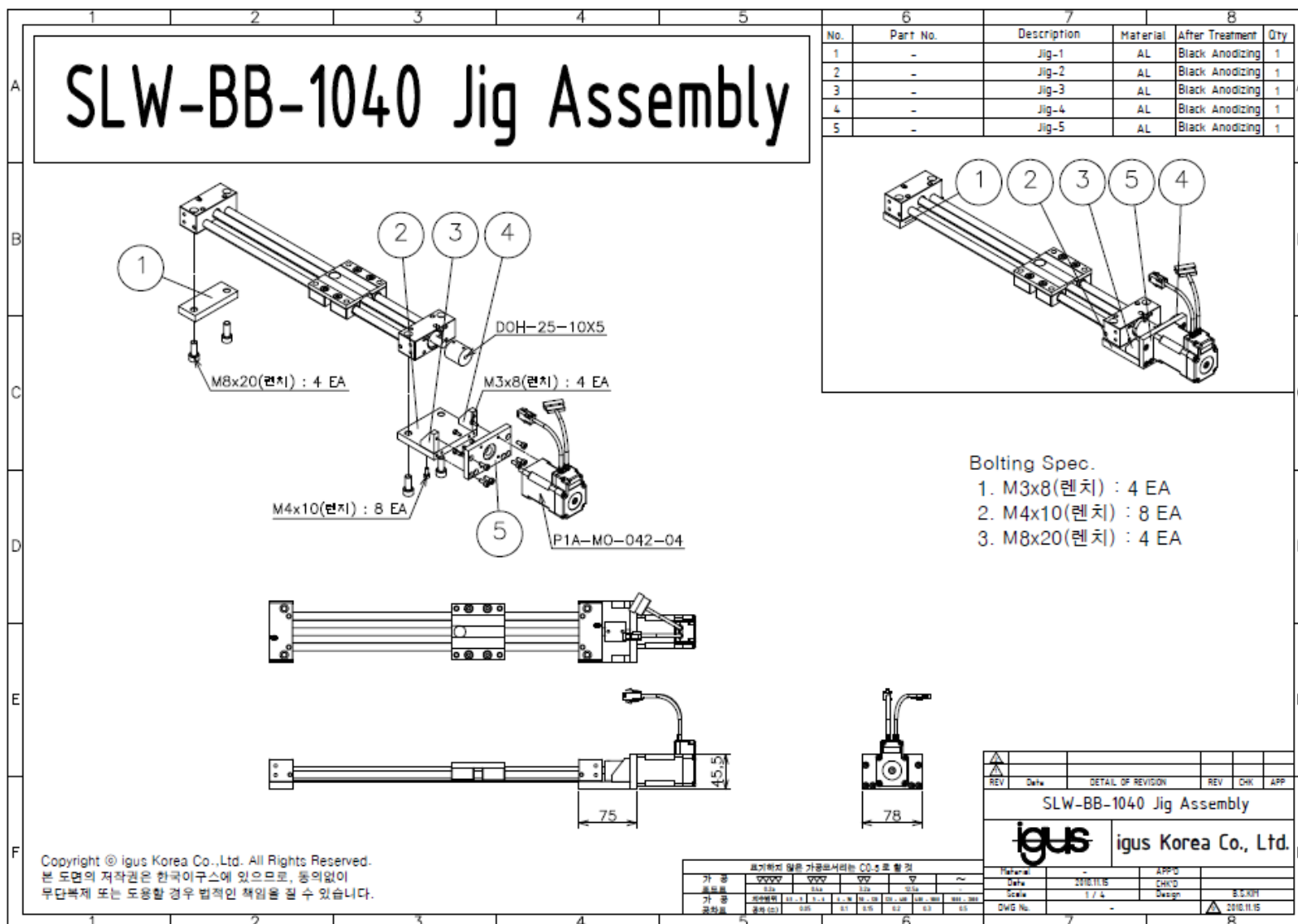


Ezi-SERVO + igus Lead screw

Ezi-SERVO + Igus drylin Actuator

- ❖ 고성능 폴리머 Sliding으로 **마찰 최소화**
- ❖ 고기능 플라스틱으로 **내 화학성, 내 부식성, 방수성**
- ❖ **무급유**, 유지보수 불 필요
- ❖ 금속 대비 **경량, 저소음**
- ❖ 다양한 산업용 **network 호환성** (Ethernet, EtherCAT, CC Link 등)

Cooperation Result (Assembly drawing)



“Ethernet” Plus E Series **Closed Loop Stepping System**

Ezi-SERVO[®] II Plus-E

Closed Loop Stepping System

Ezi-MOTIONLINK[®] Plus-E

Ezi-IO[®] Plus-E



Ezi-SERVO® II Plus-E + Ezi-MOTIONLINK® Plus-E + Ezi-IO® Plus-E

Ezi-SERVO® II Plus-E

Closed Loop Stepping System



Fast, Accurate, Smooth Motion



Closed Loop Stepping System
with embedded controller
based on **Ethernet**

“Control stepping motor,
AC Servo motor and I/O in the same
Ethernet network”



Closed Loop Stepping System
with embedded controller
based on **Ethernet**

“High speed short pitch motion”



Closed Loop Stepping System
with embedded controller
based on **Ethernet**

“High speed short pitch motion”



Closed Loop Stepping System
with embedded controller
based on **Ethernet**

“High speed short pitch motion”

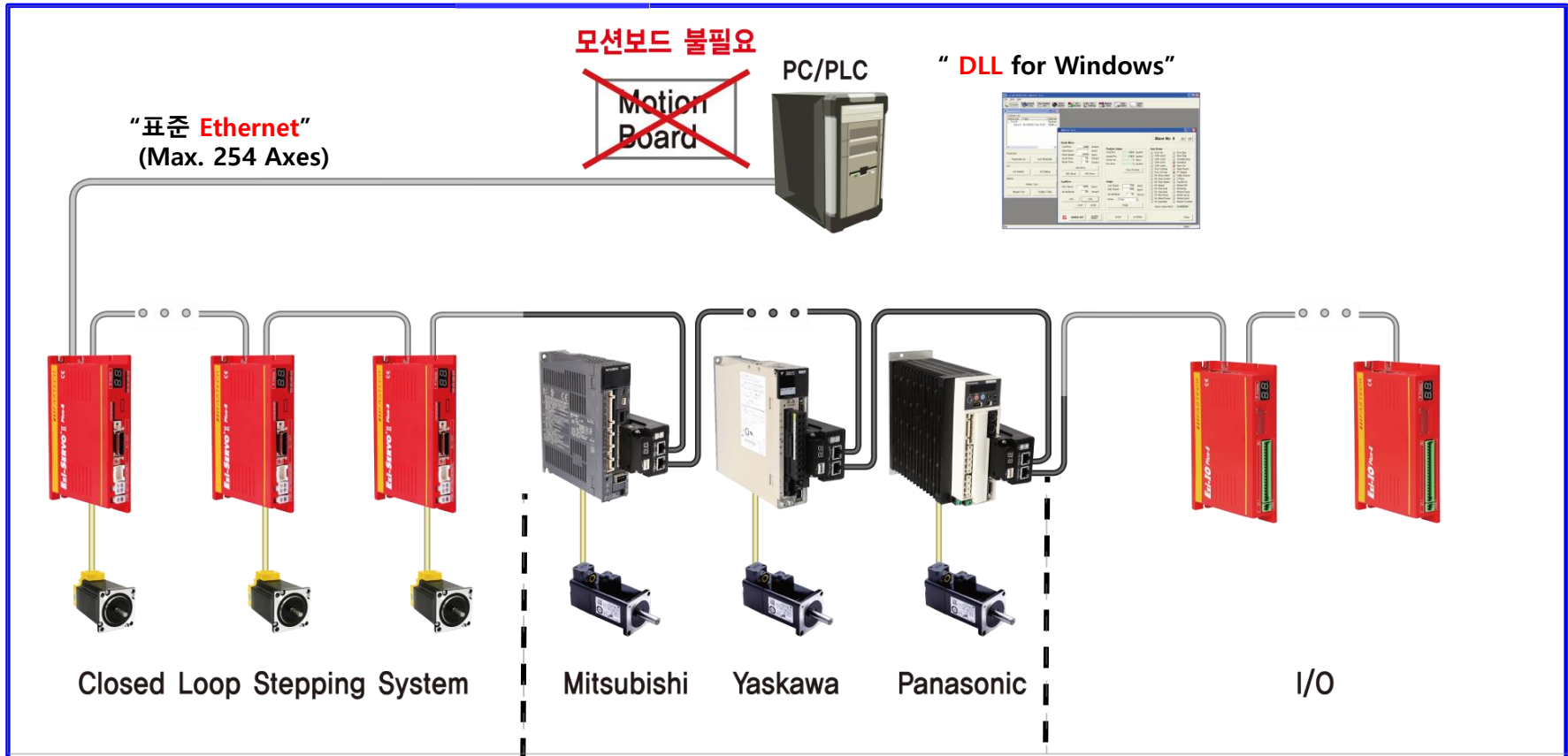


Closed Loop Stepping System
with embedded controller
based on **Ethernet**

“Push Mode (Force control)”

제품 Concept

❖ **Step Motor+Servo Motor+I/O** 를 하나의 **"Ethernet"** 연결



Ezi-SERVO® II Plus-E

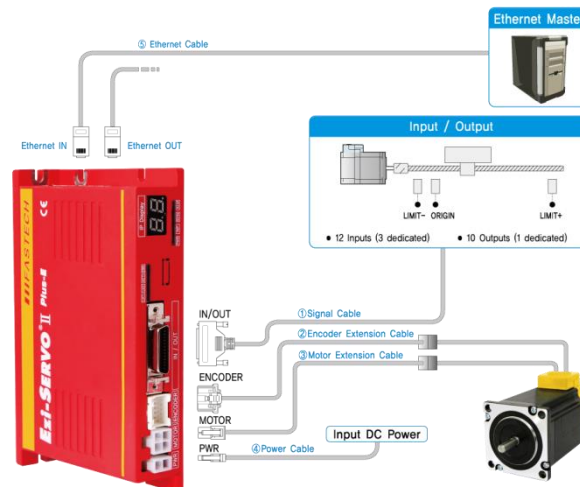
Ezi-MOTIONLINK® Plus-E

Ezi-IO® Plus-E

Ezi-SERVO®
Closed Loop Stepping System

“Ethernet 기반 Closed Loop Stepping System”

- ❖ DLL and GUI Ezi-SERVO PLUS-R 100% 프로그램 호환
- ❖ 사용자 program and FASTECH GUI 동시 접속 (Plus-R 동시 접속 불가능)
- ❖ 2 Port Switching HUB embedded(100Mbps Ethernet Port)
- ❖ Ezi-SERVO, Ezi-MotionLink Plus-E 동일 Network 구성



“Ethernet” 기반 1축 제어기

- ❖ 각종 **AC SERVO Drive** 직접 연결 (3M 50pin 커넥터 직접 연결)
- ❖ Windows Motion Library (**DLL**) and GUI 제공
- ❖ 사용자 program and FASTECH GUI **동시 접속** (**Plus-R** **동시 접속 불가능**)
- ❖ 2 Port Switching **HUB** embedded (100Mbps Ethernet Port)
- ❖ Ezi-SERVO, Ezi-MotionLink Plus-E **동일 Network** 구성

AC SERVO 3M 50 Pin
connector 직접연결



Mitsubishi



Yaskawa



Panasonic

❖ 적용 가능 Servo drives

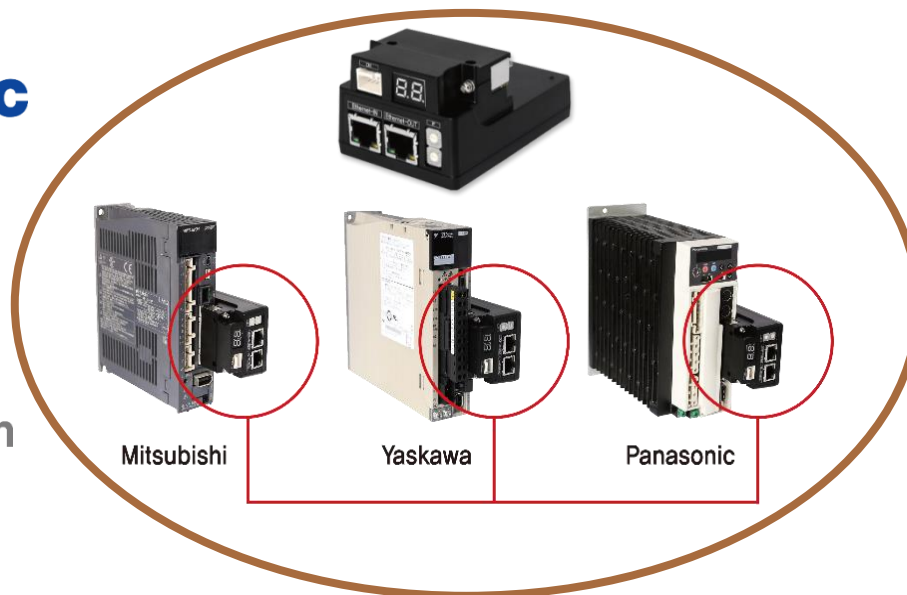
YASKAWA



Panasonic



RS Reliable & Smart
Automation



SANYO DENKI

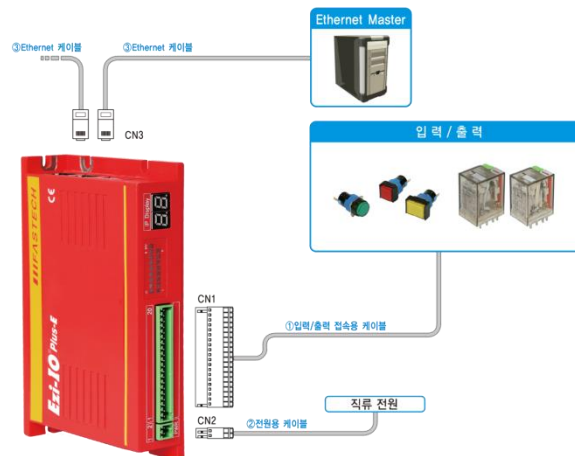
LS 메카피온

A **Nidec** Group Company
Sankyo

Ezi-SERVO[®]
Closed Loop Stepping System

“Ethernet 기반 Digital Input/Output Module”

- ❖ **16 Input** (Photocoupler input, Source/Sink, Latch function)
- ❖ **16 Output** (Photocoupler output, FET output, Trigger output function)
- ❖ Windows Motion Library(**DLL**) and GUI 제공
- ❖ 사용자 program and FASTECH GUI **동시 접속** (**Plus-R** **동시 접속 불가능**)
- ❖ 2 Port Switching HUB embedded (100Mbps Ethernet Port)
- ❖ Ezi-SERVO, Ezi-MotionLink Plus-E **동일 Network** 구성



Plus-E vs. Plus-E

- ❖ 통신 속도 **Plus-E** : Plus-R 대비 **10 times**
- ❖ 고객 프로그램, 파스텍 GUI 동시 접속 가능

2019 년 파스텍은 **Plus E**를
주력으로 판매 합니다

속도 비교(PE vs PR)

1. Ezi-SERVO II PE (평균): **0.156**[ms] (156[us])

2. Ezi-SERVO PR

1) 통신 속도 115,200(Average) : **3.561**[ms]

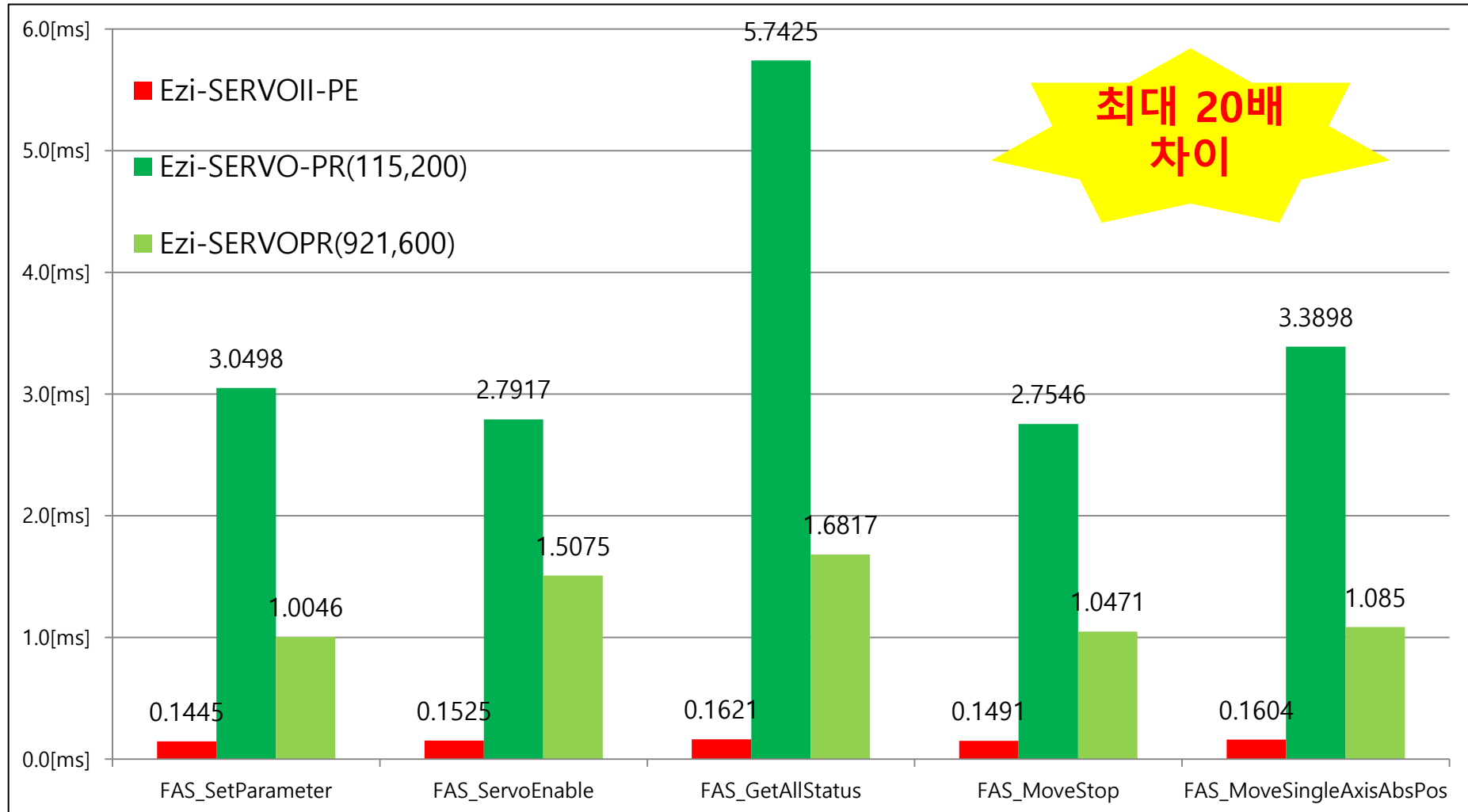
2) 통신 속도 921,600(Average) : **1.206**[ms]

❖ 115,200 : FAS-RCR 사용

❖ 921,600 : PCI-1612 (ADVANTECH PCI RS485 Board) 사용

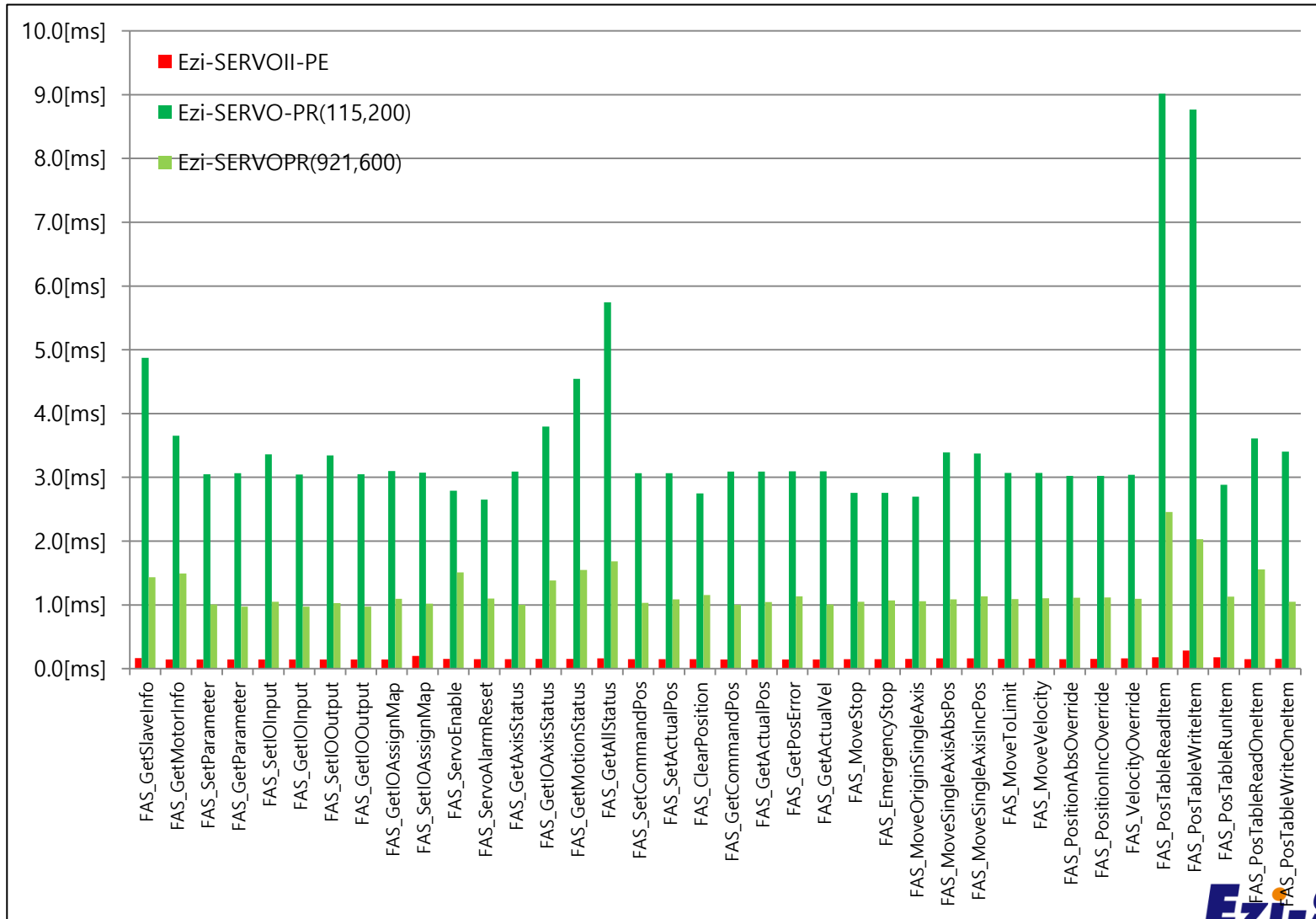
통신 속도 비교 (PE vs PR)

❖ Communication speed comparison of most used commands (Average)

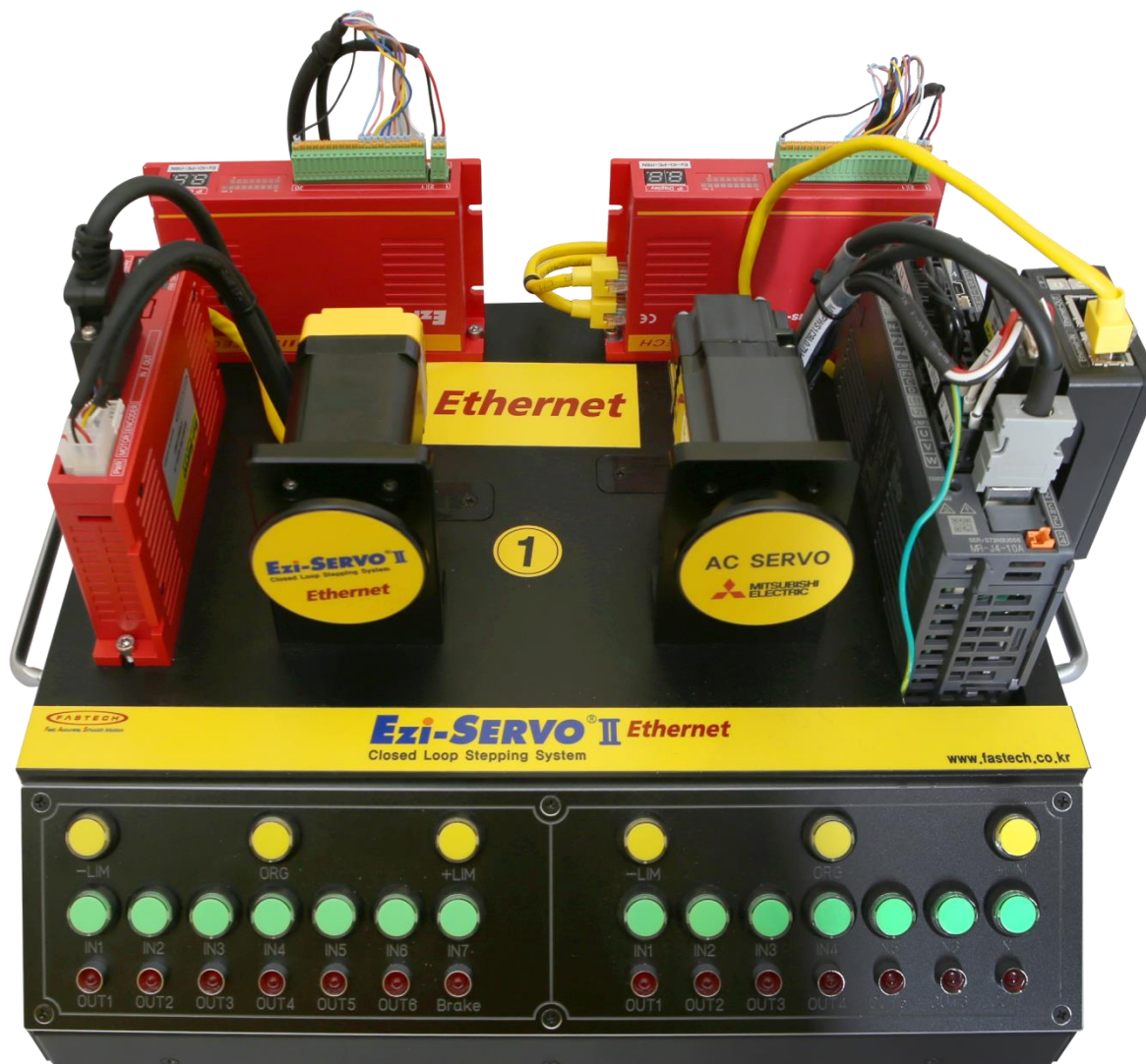


통신 속도 비교 (PE vs PR)

❖ Communication speed comparison for total command (Average)



Plus E Demo Jig



“EtherCAT” 기반 Closed Loop Stepping System

Ezi-SERVO® II EtherCAT®
Conformance tested

Closed Loop Stepping System



BECKHOFF : CX2020 BECKHOFF

Ezi-SERVO[®] II EtherCAT[™]
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



EtherCAT Network 기반
Closed Loop Stepping System

“EtherCAT 을 통한 32축 동기 제어”

Ezi-SERVO[®]
Closed Loop Stepping System



EtherCAT Network기반
Closed Loop Stepping System

“EtherCAT을 통한 Hexapod 제어”

Parker : PAC Controller



Ezi-SERVO® II EtherCAT
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



EtherCAT Network기반
Closed Loop Stepping System

“EtherCAT을 통한 Delta robot 제어”

Ezi-SERVO®
Closed Loop Stepping System



기반 Closed Loop Stepping System

- ❖ **CiA 402** Profile 지원
- ❖ **Cyclic Synchronous Position Mode (CSP)**
- ❖ **Profile Position Mode(PP)**
- ❖ Homing Mode
- ❖ Sampling Time : 0.5[msec]
- ❖ Conformance Tested (EtherCAT Technology Group)
- ❖ 주요 EtherCAT master 제품과 호환성 완료 (**FASTECH** 강점)



호환성 시험 완료 EtherCAT master

BECKHOFF

OMRON
Industrial Automation

RS Reliable & Smart
Automation

ACS
MOTION CONTROL

AJINEXTEK AXT

Elmo
Motion Control

COMIZOA

TRIO
MOTION TECHNOLOGY

LS Mecapion

**NATIONAL
INSTRUMENTS**

Parker

Soft Servo
SYSTEMS, INC



Ezi-SERVO[®]
Closed Loop Stepping System

ETG 인증 Closed Loop Stepping solutions

<https://www.ethercat.org/en/products.html>


































1 to 19 entries of 19 (filtered from 687 total entries)

<< < 1 > >>

	Company	Name	Type
	ACS Motion Control	PDicI	Drive Technology – Stepper
	ACS Motion Control	PDMnt	Drive Technology – Stepper
	ACS Motion Control	SDMnt	Drive Technology – Stepper
	AUTOMATA	SMC3 Stepper Motor Controller	Drive Technology – Stepper
	BECKHOFF Automation	Stepper Motor Terminals	Drive Technology – Stepper
Cert. ✓	Copley Controls	Stepnet Plus 1-Axis Modules	Drive Technology – Stepper
Cert. ✓	Copley Controls	Stepnet Plus 2-Axis Modules	Drive Technology – Stepper
Cert. ✓	Copley Controls	Stepnet Plus 2-Axis Panel Mount	Drive Technology – Stepper
Cert. ✓	COSMOTECHS	CTDR-0514ES-4L	Drive Technology – Stepper
Cert. ✓	FASTECH	Ezi-SERVO2 EtherCAT	Drive Technology – Stepper
Cert. ✓	Hivertec	HES-M400	Drive Technology – Stepper
	IAI	EtherCAT Field Network Controllers PCON-CA/CFA	Drive Technology – Stepper
	Kendrion Kuhnke Automation	Kuhnke FIO Drive Control Stepper / BLDC	Drive Technology – Stepper
	ORIENTAL MOTOR	Rotary Actuator DGII Series	Drive Technology – Stepper
	R.T.A.	CSD ET	Drive Technology – Stepper
	R.T.A.	Plus ET	Drive Technology – Stepper
	R.T.A.	X-Plus ET	Drive Technology – Stepper
	SANYO DENKI	SANMOTION Model No.PB	Drive Technology – Stepper

**Oriental Motor
인증 통과 못함**

EtherCAT Conformance Test Report

Maker	EtherCAT Master	Evaluation Report	Test Manual
BECKHOFF	CX2020	 160402_Ezi-SERVO_EtherCAT Evaluation Report_BECKhoff.pdf	 160412_1[Manual]_Ezi-SERVO_EC TwinCAT_ENG.pdf
	SPiiPlusEC	 Fastech Ezi-Servo2 Qualification Report_ACS.pdf	 160411_1[Manual]_Ezi-SERVO_EC ACS_ENG.pdf
	NJ501-1320	 Ezi-SERVO2 EtherCAT Evaluation Report_ENEJOB.pdf	 EziServo_A.pdf
	MC4N	 160715_Ezi-SERVO2 EtherCAT Evaluation Report_TRIO.pdf	 160406_1[Manual]_Ezi-SERVO_EC Trio-MC4N_ENG.pdf
	Gold Maestro	 160408_Ezi-SERVO2 EtherCAT Evaluation Report_ELMO.pdf	 160408_1[Manual]_Ezi-SERVO_EC Elmo Maestro_ENG.pdf
	PAC	 Ezi-SERVO2 EtherCAT Evaluation Report_Parker_PAC.pdf	 160421_1[Manual]_Ezi-SERVO_EC Parker PAC_ENG.pdf
	WMX	 160303_Ezi-SERVO2 EtherCAT Evaluation Report_Soft Servo Korea_eng.pdf	 160404_1[Manual]_Ezi-SERVO_EC SoftServo_ENG.pdf
	NI CompactRIO-903x	 160303_Ezi-SERVO2 EtherCAT Evaluation Report_NI Korea_eng.pdf	X
	CPS-PC341EC-1	 160613_Ezi-SERVO2 EtherCAT Evaluation Report_CONTEC.pdf	 CONTEC INC. 1777 E. 4100th Street, St. Paul, MN 55112, USA
	PCI-1203	 160218_Ezi-SERVO2 EtherCAT Evaluation Report_Advantech.pdf	 160204_1[Manual]_Ezi-SERVO_EC Advantech_ENG.pdf
	μRMC2	 160121_Ezi-SERVO2 EtherCAT Evaluation Report_Robox.pdf	X
	MXP V2.0	 160219_Ezi-SERVO2 EtherCAT Evaluation Report_NORIS_Mecapion_eng.pdf	 160408_1[Manual]_Ezi-SERVO_EC LS Mecapion MXP_ENG.pdf

EtherCAT Demo Jig



- Input Signal Functions
 - 3 dedicated inputs ;
Limit+, Limit-, Origin
 - 7 user inputs
- Output Signal Functions
 - 2 dedicated outputs ;
Brake+, Brake-
 - 6 user outputs

Limit+,-

Origin

7 user inputs

Brake(no need to test)

6 user outputs

Ezi-SERVO[®] II EtherCAT[®]
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



Closed Loop Stepping System
based on **EtherCAT**

“Delta robot control
through EtherCAT!!”

BECKHOFF : CX2020 BECKHOFF

Ezi-SERVO® II EtherCAT[®]
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



Closed Loop Stepping System
based on **EtherCAT**

**“IGUS 3 Axis Cantilever
Robot Control”**

Ezi-SERVO®
Closed Loop Stepping System

ACS Controller + EtherCAT ALL

Ezi-SERVO® II EtherCAT
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



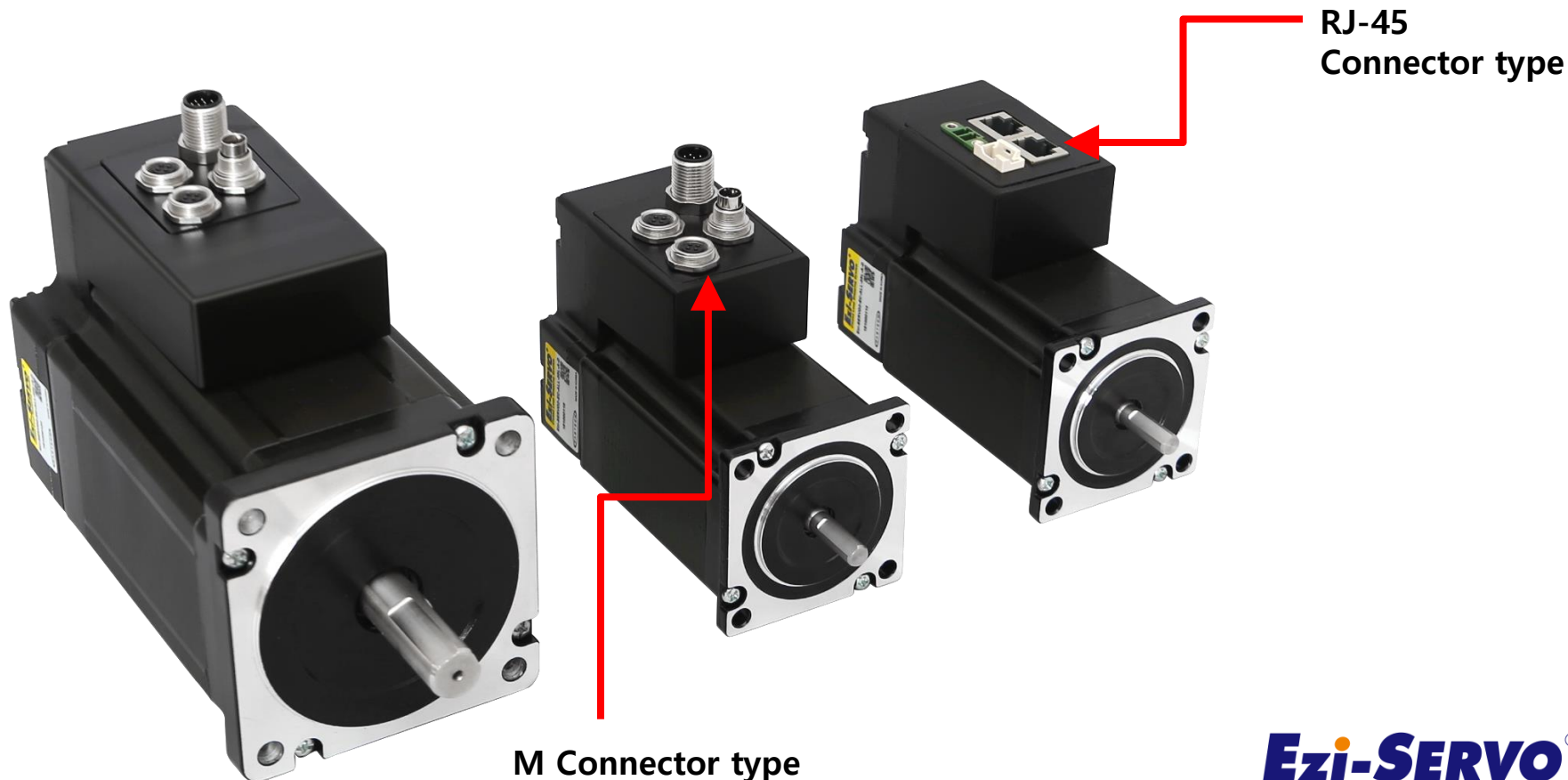
Closed Loop Stepping System
based on **EtherCAT**

“FESTO 4 axes Cantilever Robot
Control based on EtherCAT”

Ezi-SERVO®
Closed Loop Stepping System

Ezi-SERVOII EtherCAT ALL

- ❖ **M Connector type / RJ-45 Connector type**
- ❖ **Motor + Encoder + Drive + Controller + EtherCAT**
- ❖ **42, 56, 60[mm] Motor size**



Omron Controller + EtherCAT 4X

Ezi-SERVO® II EtherCAT
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



Closed Loop Stepping System
based on **EtherCAT**

“Multi-joint RoboLink”

Ezi-SERVO®
Closed Loop Stepping System

Ezi-SERVO II EtherCAT 4 Axes drive

- ❖ Rail Mount Type
- ❖ 각 drive 고유 ID
- ❖ 20 ~ 60[mm]



SSK Controller + EtherCAT IO

Ezi-IO® EtherCAT™
Input/Output Module

FASTECH
Fast, Accurate, Smooth Motion



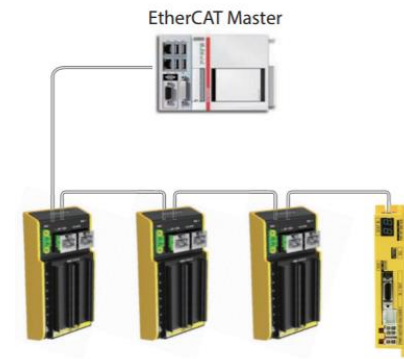
I/O Module based on **EtherCAT**

**“2 axes and I/O Module
Control through EtherCAT”**

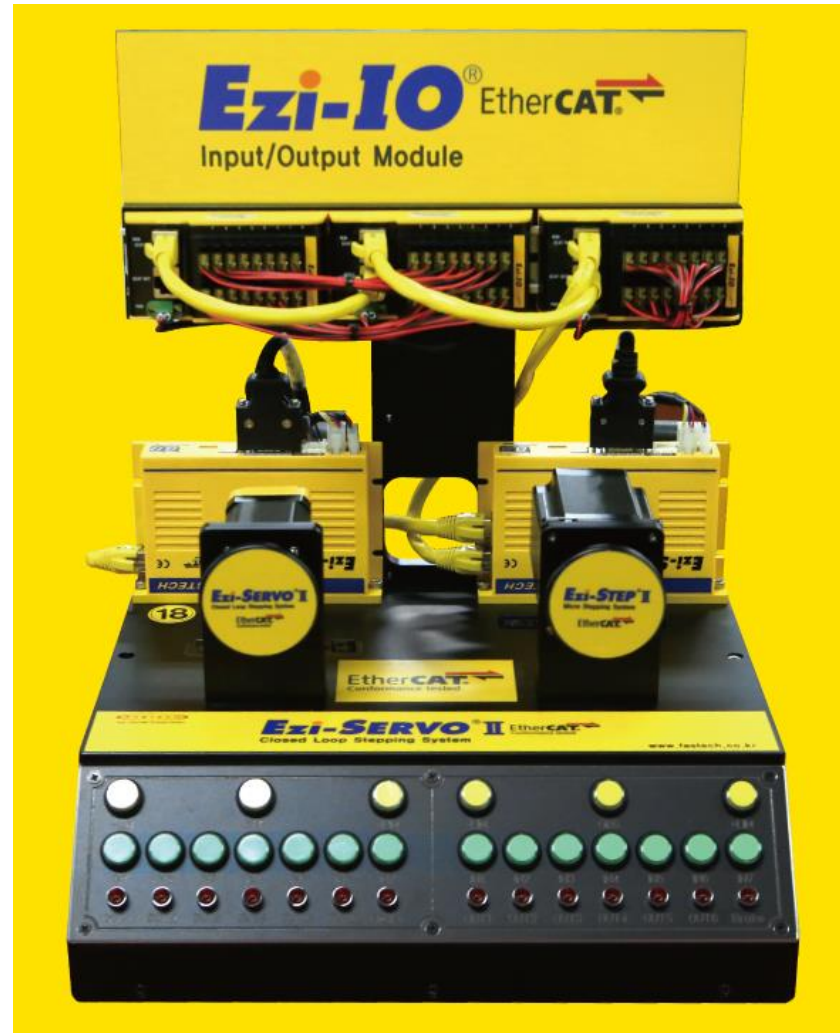
Ezi-SERVO®
Closed Loop Stepping System

Ezi-IO EtherCAT

- ❖ EtherCAT 기반 **Digital I/O** Module
- ❖ Using Standard **e-CON** connector
- ❖ 16 Input, 16 Output, 8 Input/8 Output
- ❖ **NPN/PNP** type



EtherCAT IO Demo Jig



ALL type **Closed Loop Stepping System**

Ezi-SERVO[®] ALL **Closed Loop Stepping System**



Ezi-SERVO ALL 28 Demo video

Ezi-SERVO[®] ALL
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



RS-485 타입 제어기 내장형
Closed Loop Stepping System

“3축 초소형 고속 단팻치 모션”

Ezi-SERVO[®]
Closed Loop Stepping System

Ezi-SERVO ALL 28

- ❖ **28[mm]**
- ❖ **Motor + Encoder + Drive + Controller + RS-485**
- ❖ **16,000 [ppr] Encoder resolution**



Integrated motor and drive Closed Loop Stepping System

Ezi-SERVO[®] II BT Closed Loop Stepping System



Ezi-SERVO II BT Demo video

Ezi-SERVO[®] II BT
Closed Loop Stepping System

FASTECH
Fast, Accurate, Smooth Motion



펄스 입력 타입 모터 +
엔코더 + **드라이브** 일체형
Closed Loop Stepping System

“고속 단펫치 모션”

Ezi-SERVO[®]
Closed Loop Stepping System

Ezi-SERVO II BT

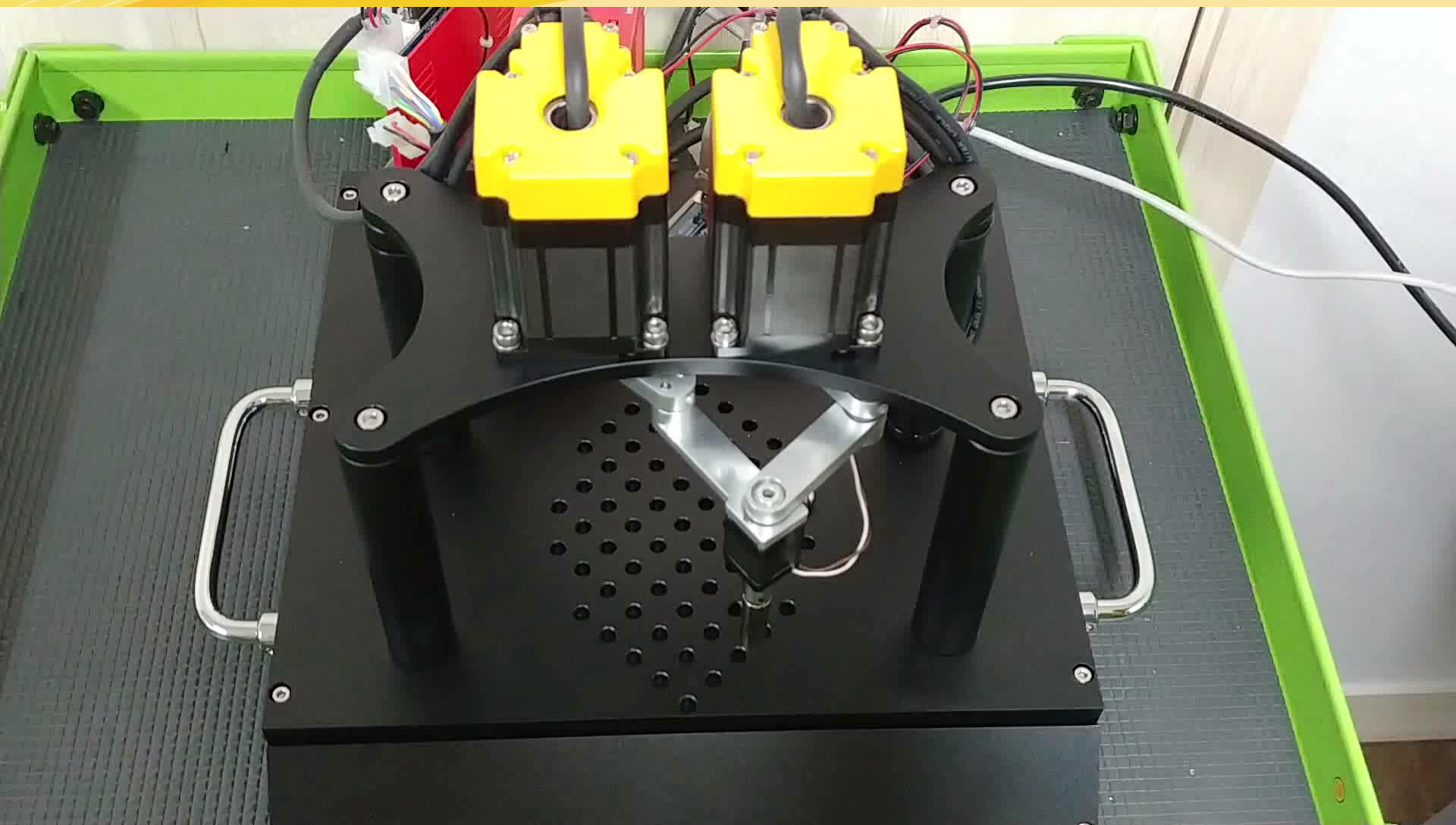
- ❖ 42, 56, **60**[mm]
- ❖ Motor + Encoder + Drive
- ❖ Pulse/Direction type
- ❖ 10,000, 20,000 [ppr] Encoder resolution



Hollow Shaft Motor Closed Loop Stepping System



Ezi-SERVO Hollow Motor



Hollow Shaft Stepper Motor

- ❖ 20~86[mm] Motor size
- ❖ S, M(1 stack, 2 stack)

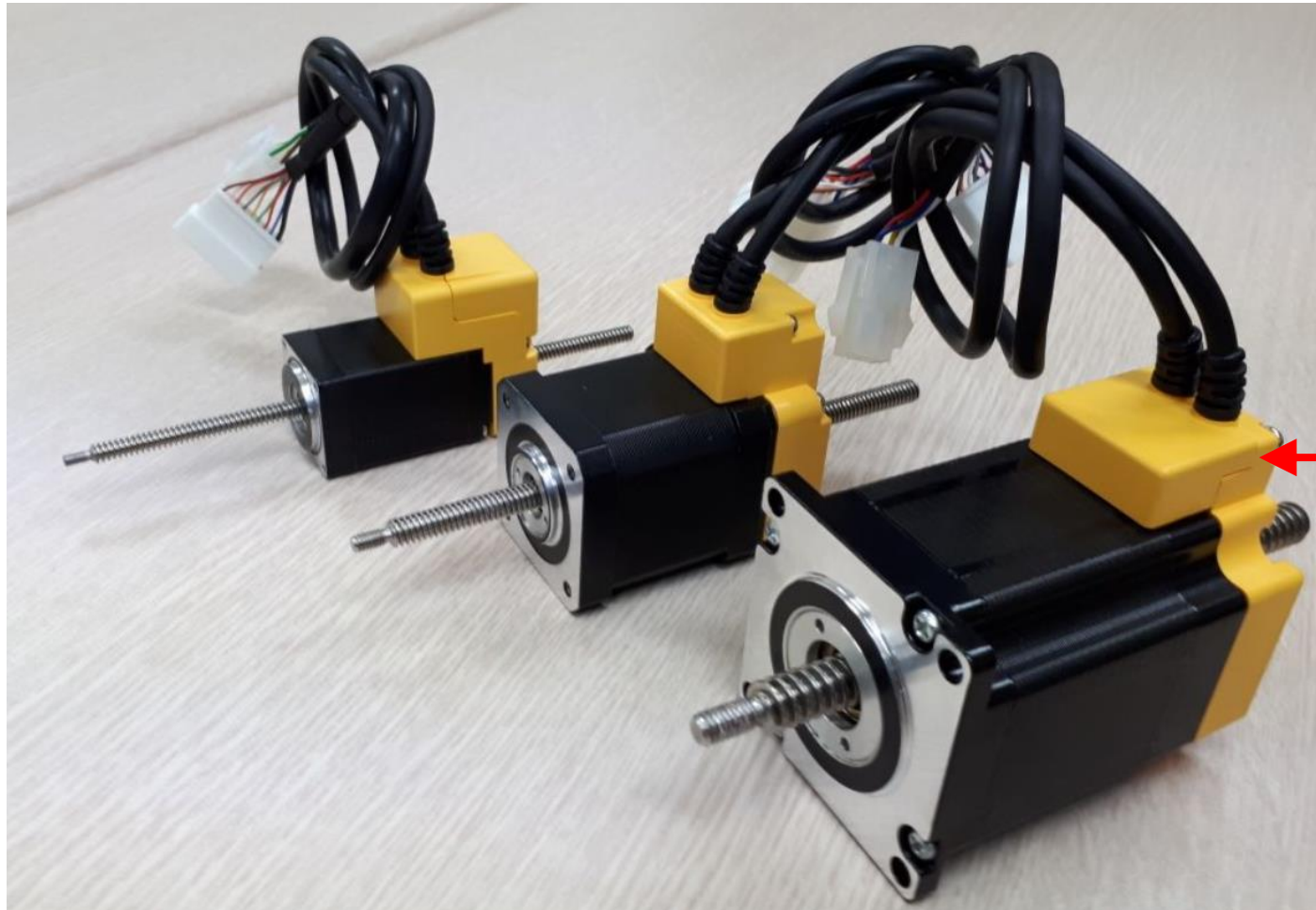


Encoder type
28~86[mm]



Encoder Mounted Non-Captive Linearstep

- ❖ 28, 42, 56[mm] Motor size
- ❖ 10,000[ppr]



Encoder

Encoder Mounted Kaptive Linearstep

- ❖ 28~86[mm] Motor size
- ❖ 10,000[ppr]



Encoder

"CC-Link" based Closed Loop Stepping System

Ezi-SERVO[®] II CC-Link
Closed Loop Stepping System



FESTO

FASTECH
Fast, Accurate, Smooth Motion



CC-Link Network 기반
Closed Loop Stepping System

“CC-Link 를 통한
FESTO H-Portal 고속 단핏치 모션”



CC-Link 타입 제어기 내장형
Closed Loop Stepping System

“8축 고속 단펫치 모션”

“CC-Link 기반 Closed Loop Stepping System”

- ❖ 100% Mitsubishi PLC 호환 (CC-Link 1.0 support)
- ❖ 원격 Device station (Station #1~#2 점유)
- ❖ CC-Link network 로 Operation command setting and 데이터 읽기/쓰기
- ❖ 정밀 위치 제어 (고정도 encoder)
- ❖ Boost current control(Max 150%) Torque 증대
- ❖ 간편 배선



Remote Device

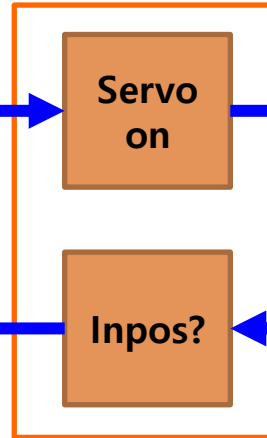
- 원격 **Device** (Bit, Word)
- Station #1 or #2 점유 (Memory allocation)

- Station #1 : 32bit I/O[0 ~ 1F] 4 word (Position Table 에 의한 동작)
- Station #2 : 64bit I/O[0 ~ 3F] 8word (Communication command에 의한 동작)

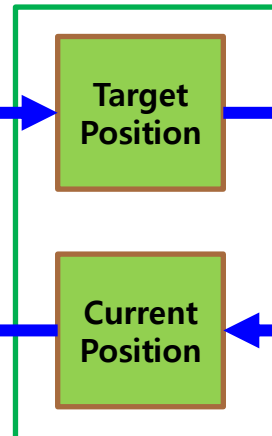
CC-Link Controller



Remote I/O
(Bit Control)



Remote Register
(Word Control)



Ezi-SERVO II CC-Link
Closed Loop Stepping System



Station #1 : 42 axis
Station #2 : 32 axis

Ezi-SERVO[®]
Closed Loop Stepping System

Remote Device MAP

1 국 점유 I/O Device Map

RY	Output Device Name	RX	Input Device Name
RY00	Servo Enable	RX00	Servo Enabled
RY01	/Emergency Stop	RX01	Emergency Stopped
RY02	ALARM RESET	RX02	ALARM Status
RY03	Homing Start	RX03	Homing
RY04	JOG +	RX04	Homing OK
RY05	JOG -	RX05	Jog Response
RY06	Step + Move	RX06	Step Move Response
RY07	Step - Move	RX07	In-Position
RY08	STOP	RX08	MOTIONING
RY09	HOLD	RX09	Hold status
RY0A	Go Zero Position	RX0A	Go Zero Position Resp.
RY0B	PT Start	RX0B	PT Running
RY0C	Single PT Select	RX0C	Single PT Select Resp.
RY0D	-	RX0D	Command Set Resp.
RY0E	Command Set	RX0E	Warning
RY0F	Motion / Setting	RX0F	Motion / Setting Resp.
RY10 ~ RY13	Step Move Position (1~10) BCD data (Parameter : Multiple of Pn#B030)	RX10 ~ RX13	Step Move Position Resp. (1~10) BCD data The square of X 10(Parameter value)
RY14 ~ RY17	Monitor code(Motion) PT Command (Teaching)	RX14 ~ RX17	Monitor code(Motion Mode) Data Code (Setting Mode) Response
RY18 ~ RY1B	Command Code	RX18 ~ RX1B	Command Code Resp.
RY1C	Cyclic Transmission Signals	RX1C	Cyclic Transmission Signals
RY1D		RX1D	CC-Link Scanning
RY1E	RS-485 Port Connect	RX1E	RS-485 Port Connect Resp.
RY1F		RX1F	RS-485 Port Connection State
RWw 0	Operation speed (Position Move, JOG Move)	RWw 0	Monitor response data(Motion) Response data(Setting)
RWw 2	PT No. / Parameter Code	RWw 2	PT No. / Parameter Code Resp.
RWw 3		RWw 3	Warning Code

2 국 점유 I/O Device Map

RY	Output Device Name	RX	Input Device Name
RX20		RX20	H/W Limit +
RX21		RX21	H/W Limit -
RX22		RX22	Org Sensor
RX23		RX23	Input Pin 1
RX24		RX24	Input Pin 2
RX25		RX25	Input Pin 3
RX26		RX26	Input Pin 4
RX27		RX27	Input Pin 5
RX28		RX28	Input Pin 6
RX29		RX29	Input Pin 7
RX2A	User Output 1	RX2A	Output Pin 1
RX2B	User Output 2	RX2B	Output Pin 2
RX2C	User Output 3	RX2C	Output Pin 3
RX2D	User Output 4	RX2D	Output Pin 4
RX2E	User Output 5	RX2E	Output Pin 5
RX2F	User Output 6	RX2F	Output Pin 6
RX30	ABS Position Move	RX30	ABS Position Move Resp.
RX31	INC Position Move	RX31	INC Position Move Resp.
RX32		RX32	
RX33		RX33	Motion Accel
RX34	Position Override	RX34	Motion Decel
RX35		RX35	Z Phase
RX36	Position Move Speed Override	RX36	S/W Limit +
RX37		RX37	S/W Limit -
RX38 ~ RX3B	Monitor code(2)	RX38 ~ RX3B	Monitor code (2) Response
RX3C ~ RX3F	Monitor code(3)	RX3C ~ RX3F	Monitor code (3) Response
RWw 0		RWw 0	
RWw 1	Position value (ABS Move, INC Move Pos)	RWw0 RWw1	Monitor response data(2)
RWw 2	Accel Time (ABS Move, INC Move Pos)	RWw2 RWw3	Monitor response data(3)
RWw 3	Decel Time (ABS Move, INC Move Pos)		

CC-Link Demo Jig





Fast, Accurate, Smooth Motion Control

"AC input BLDC motor speed control system"

Ezi-SPEED[®]

BLDC Motor Speed Control System



Ezi-SERVO[®]
Closed Loop Stepping System



BLDC Motor Speed Control System

“Ezi-SPEED와 AC 인덕션 모터 비교”



BLDC Motor Speed Control System

“Ezi-SPEED 를 이용한 2단 변속
검사 라인 컨베이어”



BLDC Motor Speed Control System

“Agitator DEMO with Ezi-SPEED”

Ezi-SPEED[®]
BLDC Motor Speed Control System

FASTECH
Fast, Accurate, Smooth Motion



BLDC Motor Speed Control System

“Ezi-SPEED DATA 모드를 이용한 8속 운전”

Ezi-SERVO[®]
Closed Loop Stepping System

FASTECH에서 새로이 선보이는 속도제어 시스템!!

- 드라이브 + BLDC motor + Gearhead (option)

- ❖ AC input BLDC motor speed control system (**Full Digital**)
- ❖ 간단 속도 제어, 간단 접속 가능
- ❖ 최고 속도 : **4,000rpm**
- ❖ 안정된 속도 제어 : 속도 변동률 **0.2% 이하**
- ❖ 높은 속도비 : 1:80 (50~4,000rpm)
- ❖ **8단 속도** 변경 가능
- ❖ 30W, 60W, 120W, 200W, 400W line-up
- ❖ 원가 절감 : 경쟁사 대비 약 **30% 절감** 가능



Ezi-SPEED Demo Jig



우리는 40년 Stepping Motor의 역사를 바꾸는 주인공입니다!!

